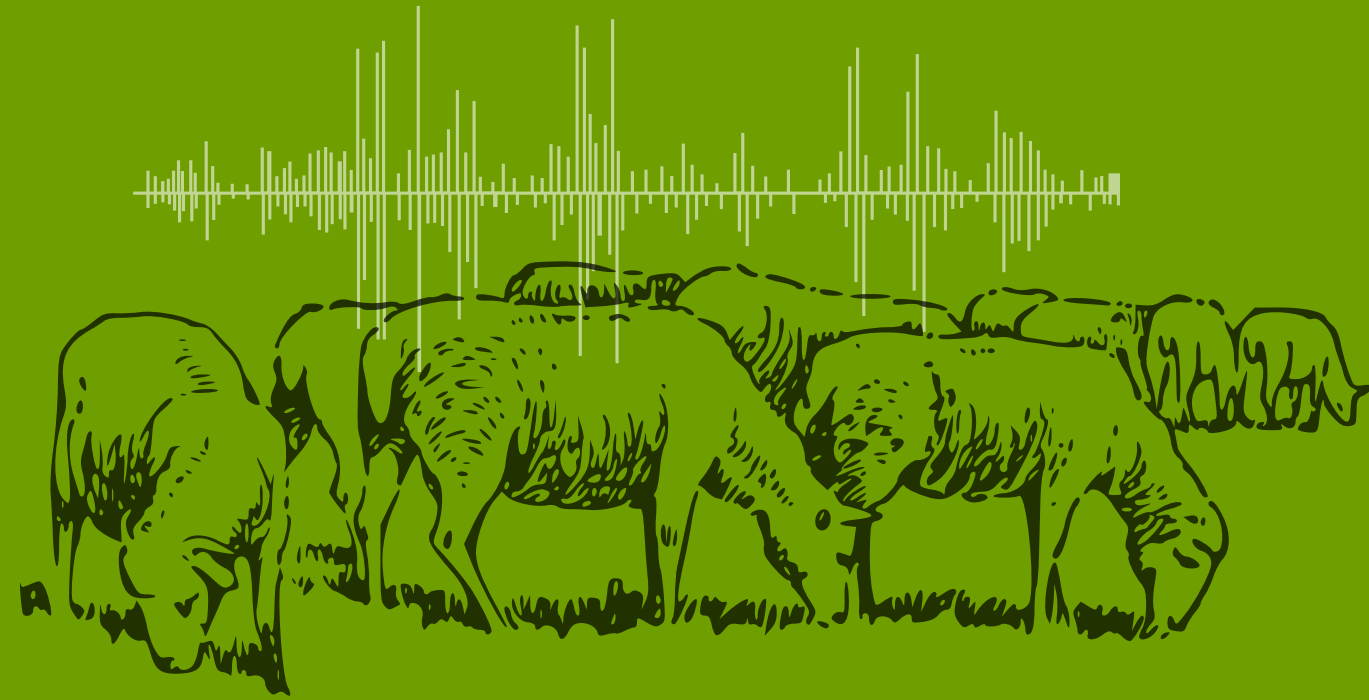




AUTOMATIC RECOGNITION OF HERBAGE PREHENSIONS IN GRAZING EWES

S. Bognanno, R. Avanzato, L. Beritelli, F. Beritelli, F. Gimmillaro, M. Avondo

PROBLEMATIC

Monitoring of feeding behaviour on pasture represents one of the fundamental challenges for PLF, especially in extensive systems.





DIRECT OBSERVATIONS

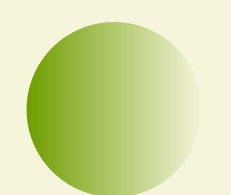
1

Traditional method.
Expensive and subject to interobserver variability.

ACCELEROMETERS

2

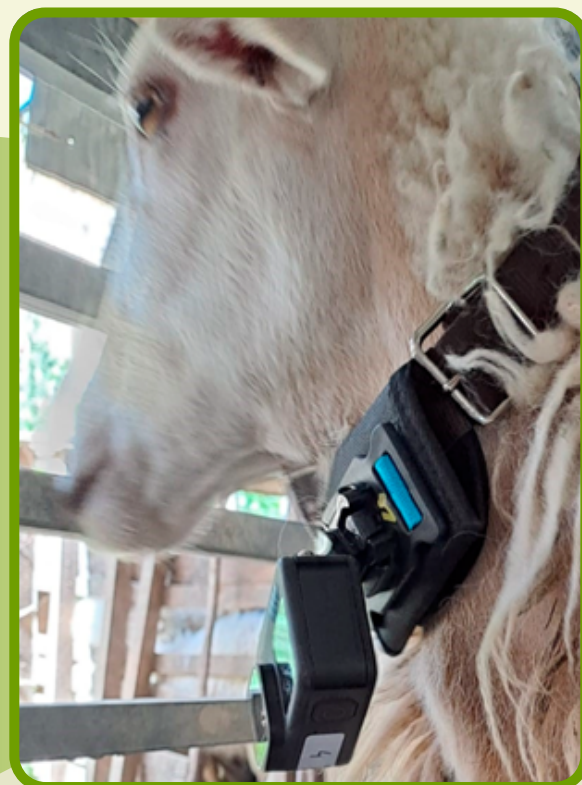
Inertial sensors (X, Y, Z) that record posture and dynamic movement intensity to automatically classify grazing, rumination and resting.



Three green circles of varying sizes are positioned in the upper half of the slide. One is at the top center, another is to its right and slightly lower, and a third is further to the right and lower still. A large, faint green circle is also visible in the bottom left corner.

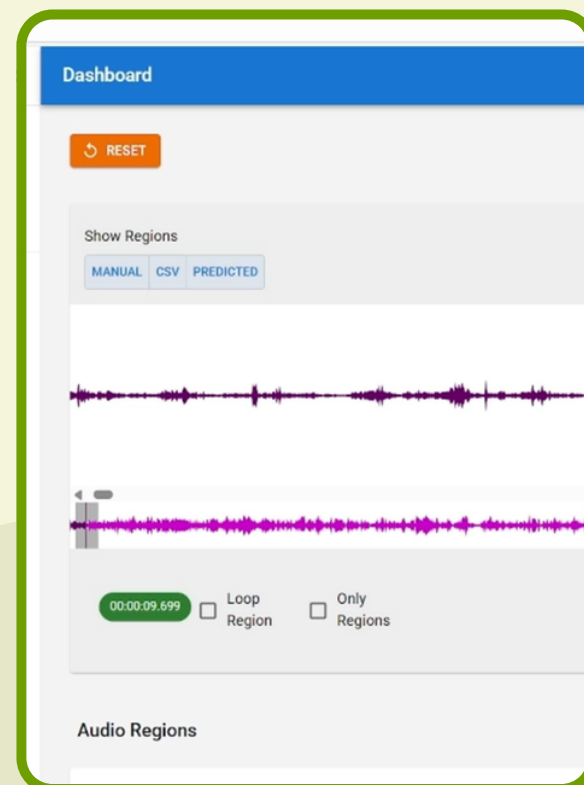
ACOUSTIC TECHNOLOGIES

Exploit distinctive bite and prehension patterns allowing events to be classified.



Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

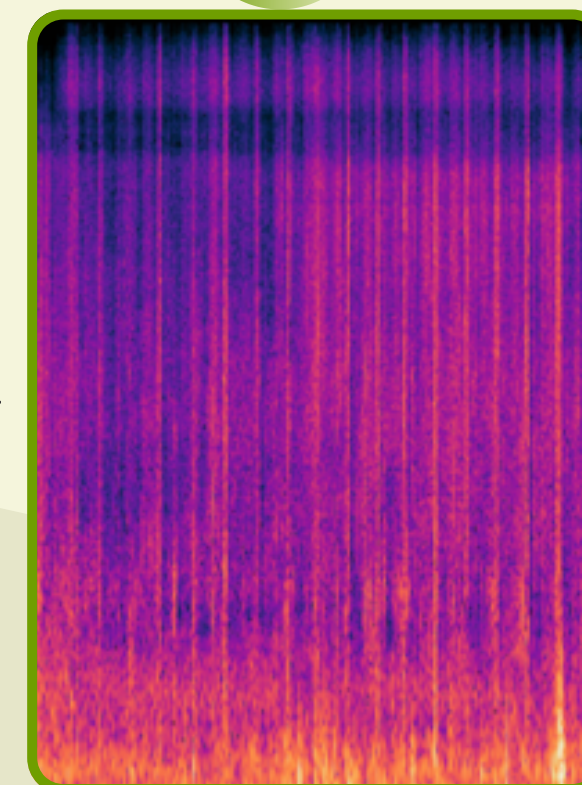
Pattern recognition of prehension events



A	B	C
start_ts	end_ts	
00:00:10.5	00:00:10.743	
00:00:11.3	00:00:11.623	
00:00:12.1	00:00:12.325	
00:00:12.7	00:00:12.992	
00:00:13.5	00:00:13.703	
00:00:14.1	00:00:14.458	
00:00:14.8	00:00:15.205	
00:00:15.8	00:00:16.121	
00:00:16.7	00:00:16.938	
00:00:17.6	00:00:17.783	
00:00:18.4	00:00:18.752	
00:00:19.1	00:00:19.329	
00:00:19.8	00:00:20.147	

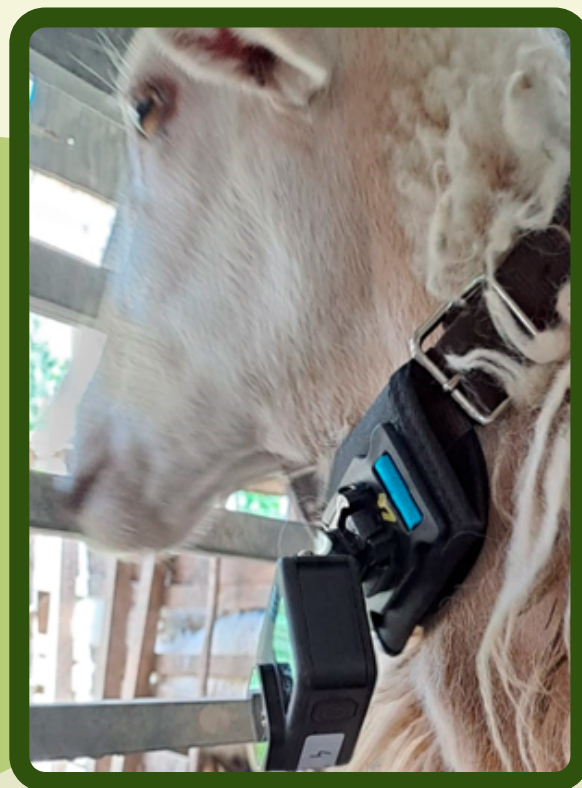
Prehension events output

Timing and number of bites



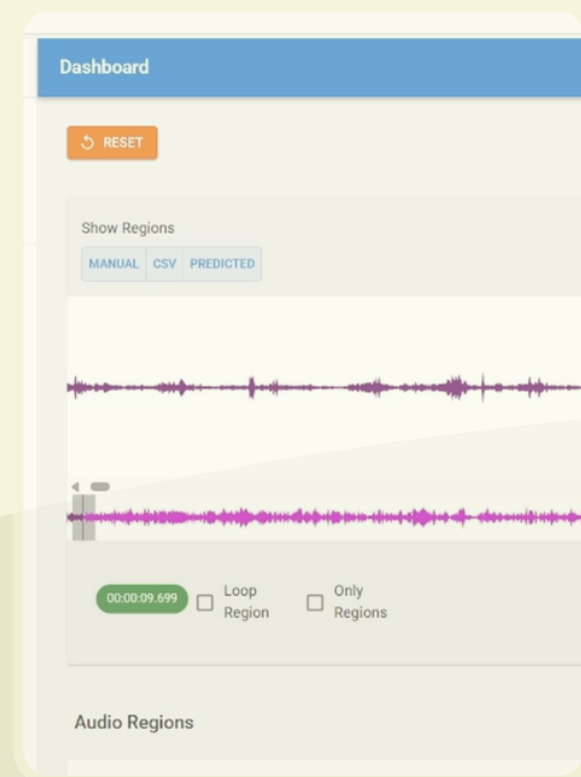
Spectrogram generation

Time-frequency representation



Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

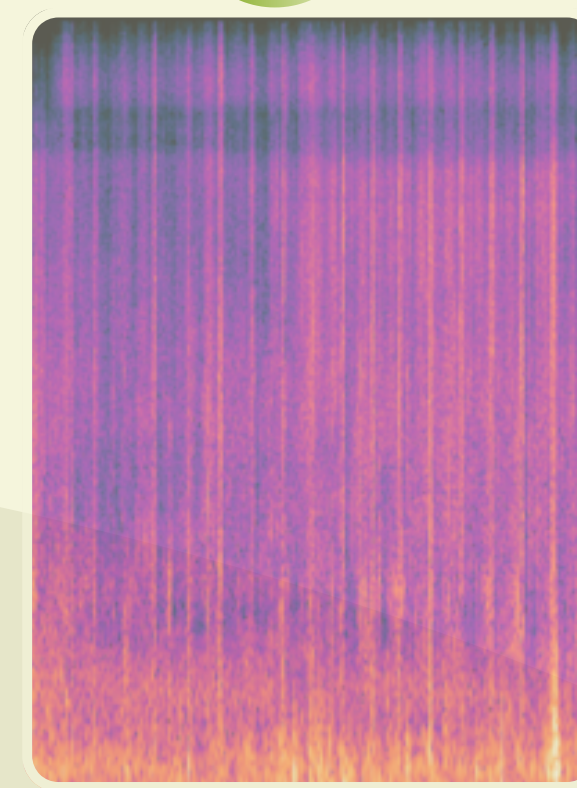
Pattern recognition of prehension events



A	B	C
start_ts	end_ts	
00:00:10.5	00:00:10.743	
00:00:11.3	00:00:11.623	
00:00:12.1	00:00:12.325	
00:00:12.7	00:00:12.992	
00:00:13.5	00:00:13.703	
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00:00:17.6	00:00:17.783	
00:00:18.4	00:00:18.752	
00:00:19.1	00:00:19.329	
00:00:19.8	00:00:20.147	

Prehension events output

Timing and number of bites



Spectrogram generation

Time-frequency representation

Acoustic data

File upload

Deep learning classification

Prehension events output

Spectrogram generation

ACOUSTIC DATA ACQUISITION

1

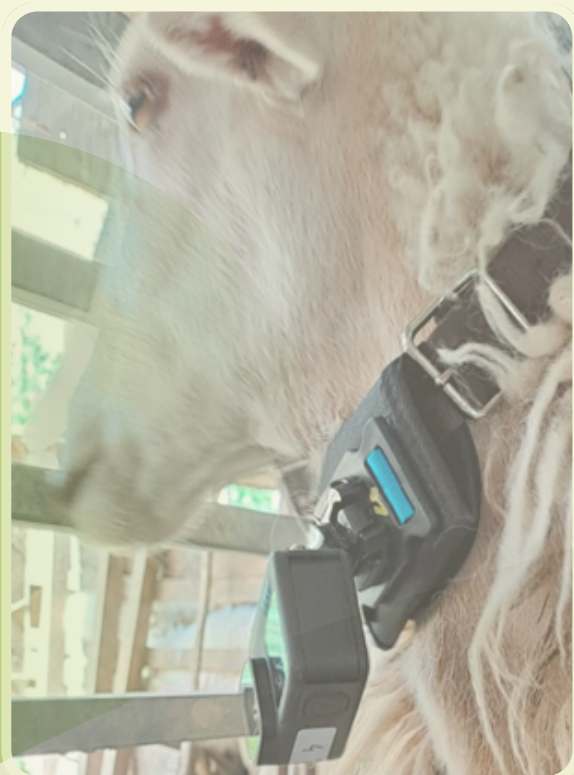
Microphone collars

2

Audio file in WAV format

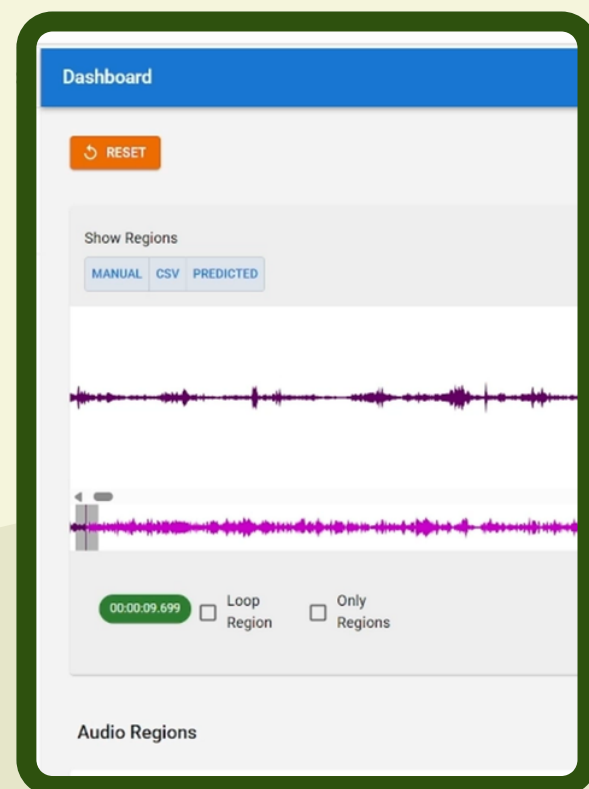






Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

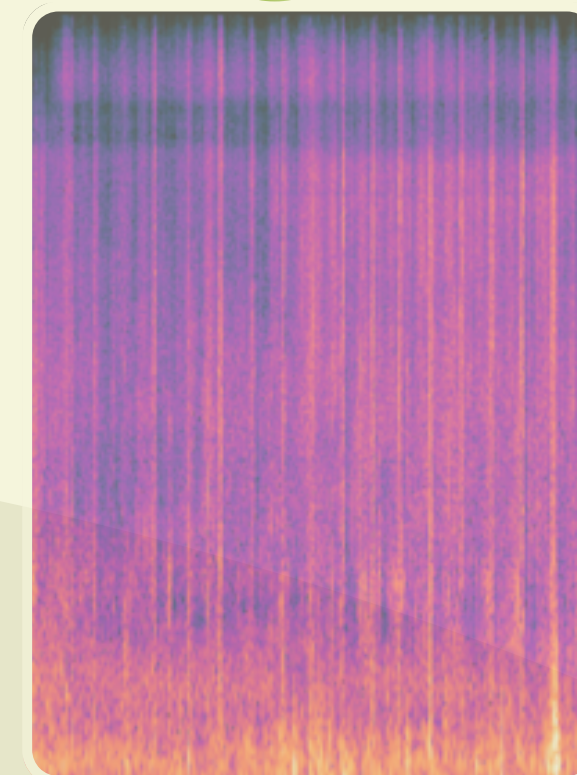
Pattern recognition of prehension events



A	B	C
start_ts	end_ts	
00:00:10.5	00:00:10.743	
00:00:11.3	00:00:11.623	
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00:00:17.6	00:00:17.783	
00:00:18.4	00:00:18.752	
00:00:19.1	00:00:19.329	
00:00:19.8	00:00:20.147	

Prehension events output

Timing and number of bites



Spectrogram generation

Time-frequency representation

Acoustcc data

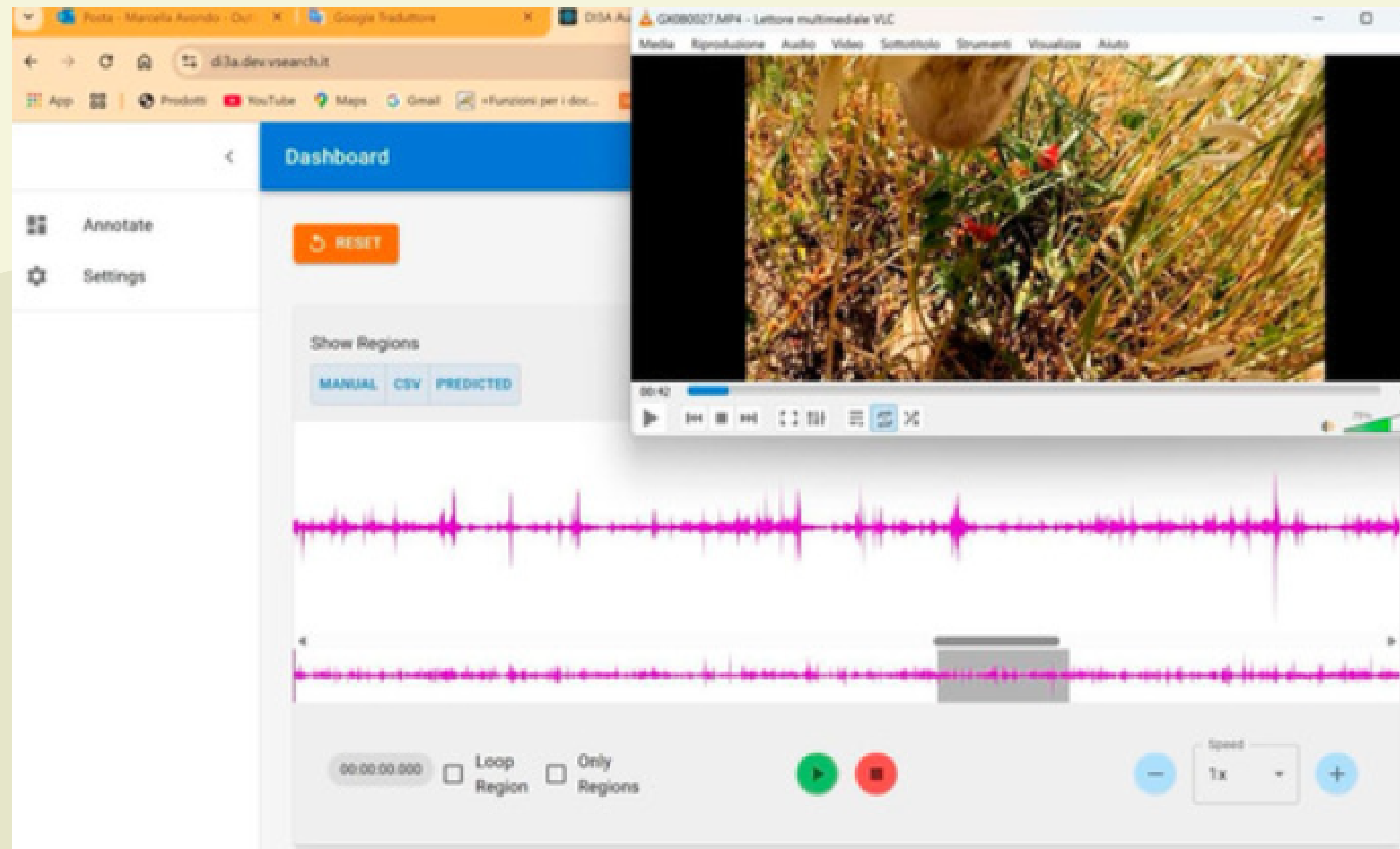
File upload

Deep learning classification

Prehension events output

Spectrogram generation

FILE UPLOAD



Acoustcc data

File upload

Deep learning classification

Prehension events output

Spectrogram generation

Browser tabs: Homepage - Canva, j - Presentazione, DI3A Audio Labeller, Sound and Video Detection as, Program Booklet and Book of A

Address bar: di3a.dev.vsearch.it/#/

Buttons: Installa, Termina aggiornamento, Tutti i preferiti

Dashboard

Left sidebar:

- Annotate
- Target/Predicted Comparison
- Settings

Top right buttons: RESET, UPLOAD CSV, DOWNLOAD CSV, PREDICT

Show Regions: MANUAL, CSV, PREDICTED

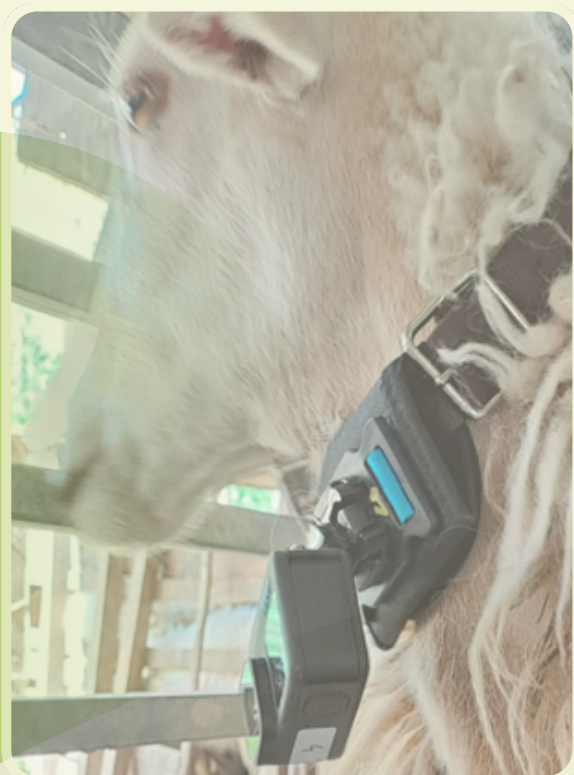
Audio waveform visualization

Timeline: 00:02:57.766, Loop Region, Only Regions

Speed: 0.75x

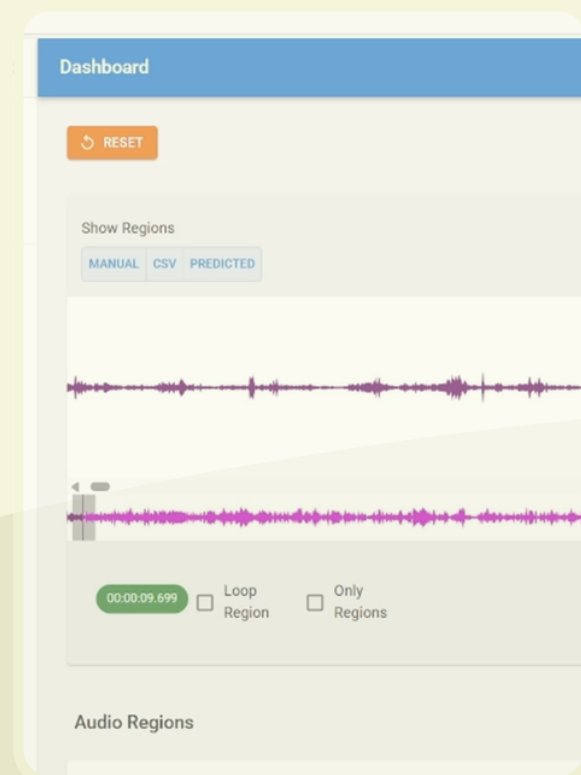
Audio Regions

No regions found

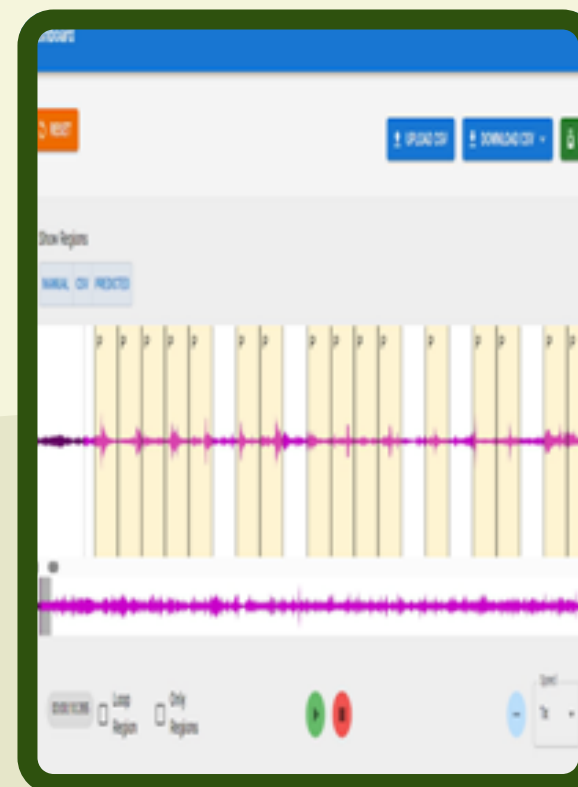


Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

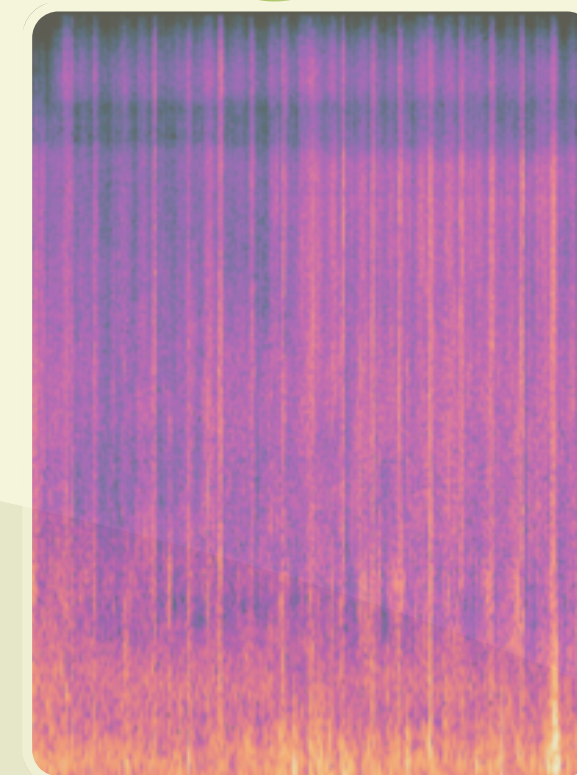
Pattern recognition of prehension events



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start_ts	end_ts	
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00:00:15.8	00:00:16.121	
00:00:16.7	00:00:16.938	
00:00:17.6	00:00:17.783	
00:00:18.4	00:00:18.752	
00:00:19.1	00:00:19.329	
00:00:19.8	00:00:20.147	

Prehension events output

Timing and number of bites



Spectrogram generation

Time-frequency representation

Acoustcc data

File upload

Deep learning classification

Prehension events output

Spectrogram generation

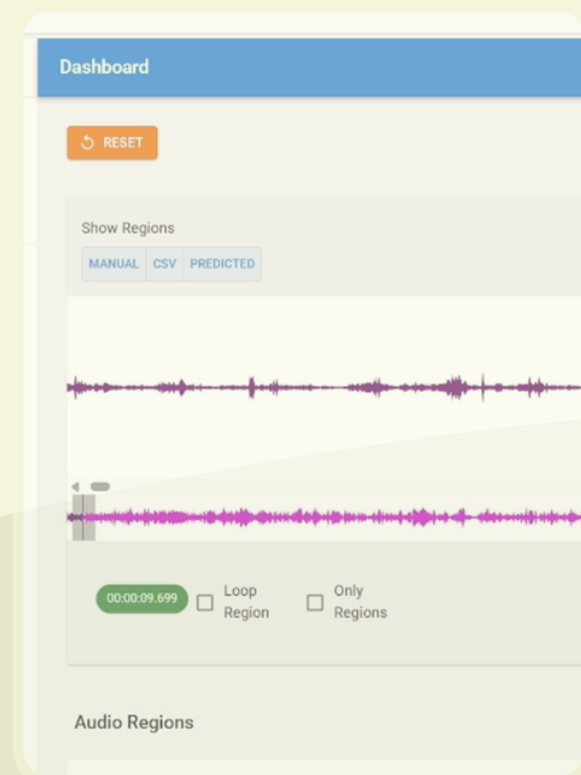
DEEP LEARNING CLASSIFICATION





Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

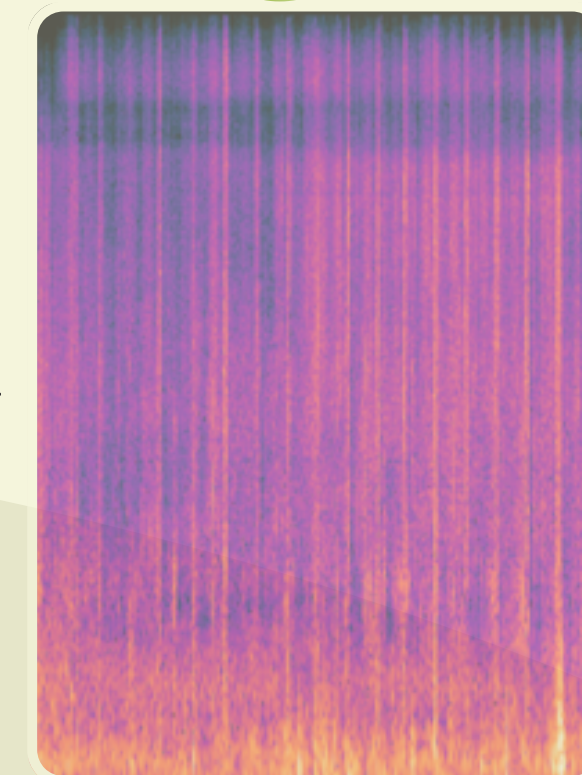
Pattern recognition of prehension events



A	B	C
start_ts	end_ts	
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00:00:11.3	00:00:11.623	
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00:00:15.8	00:00:16.121	
00:00:16.7	00:00:16.938	
00:00:17.6	00:00:17.783	
00:00:18.4	00:00:18.752	
00:00:19.1	00:00:19.329	
00:00:19.6	00:00:20.147	

Prehension events output

Timing and number of bites

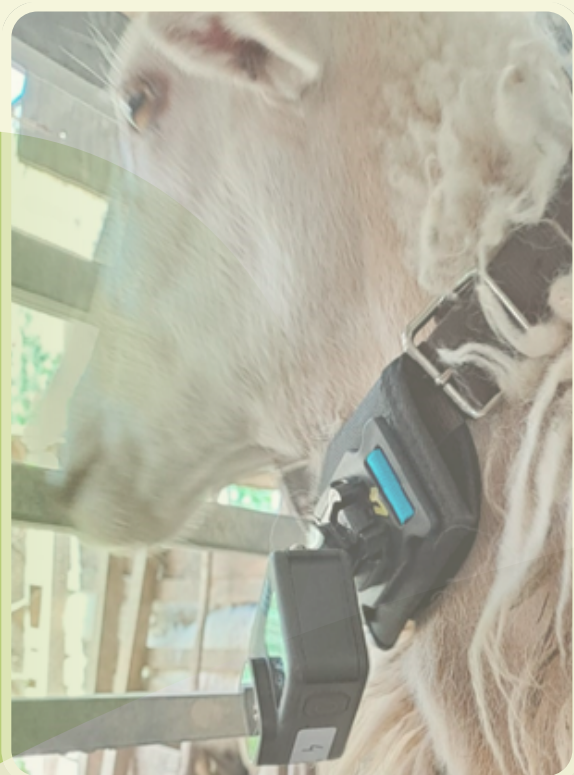


Spectrogram generation

Time-frequency representation

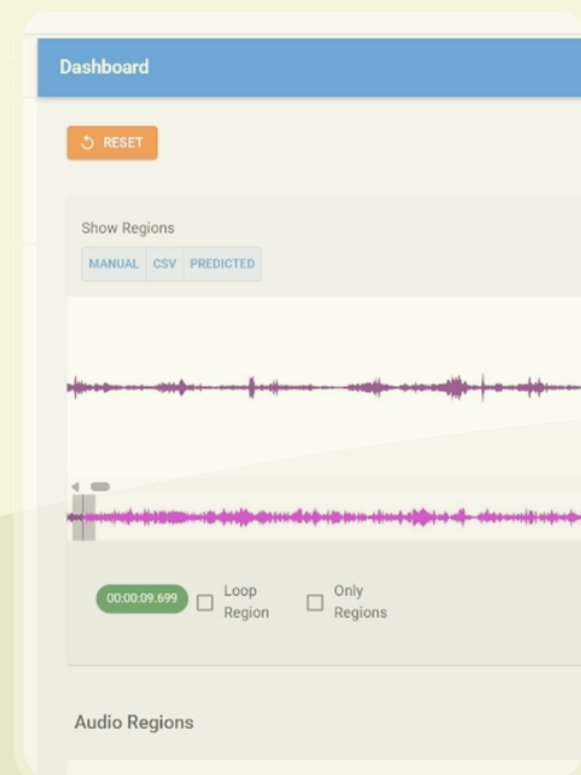
PREHENSION EVENTS OUTPUT

5	00:00:06.3	00:00:06.750
6	00:00:07.7	00:00:08.058
7	00:00:08.5	00:00:09.000
8	00:00:09.6	00:00:09.846
9	00:00:10.0	00:00:10.500
10	00:00:10.5	00:00:11.000
11	00:00:13.0	00:00:13.500
12	00:00:13.5	00:00:14.000
13	00:00:15.2	00:00:15.642
14	00:00:16.5	00:00:17.000



Acoustic data acquisition

Collar-mounted microphone and POV camera



File upload



Deep learning classification

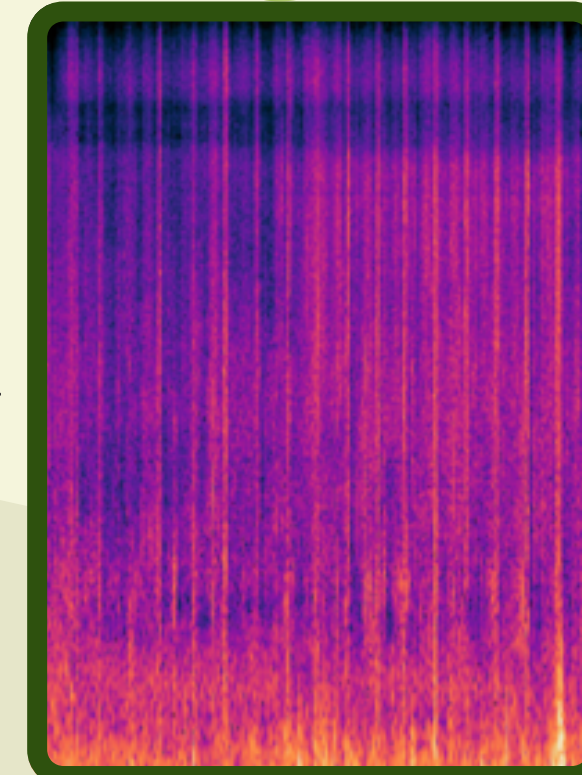
Pattern recognition of prehension events



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00:00:11.3	00:00:11.623	
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00:00:17.6	00:00:17.783	
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00:00:19.8	00:00:20.147	

Prehension events output

Timing and number of bites



Spectrogram generation

Time-frequency representation

Acoustcc data

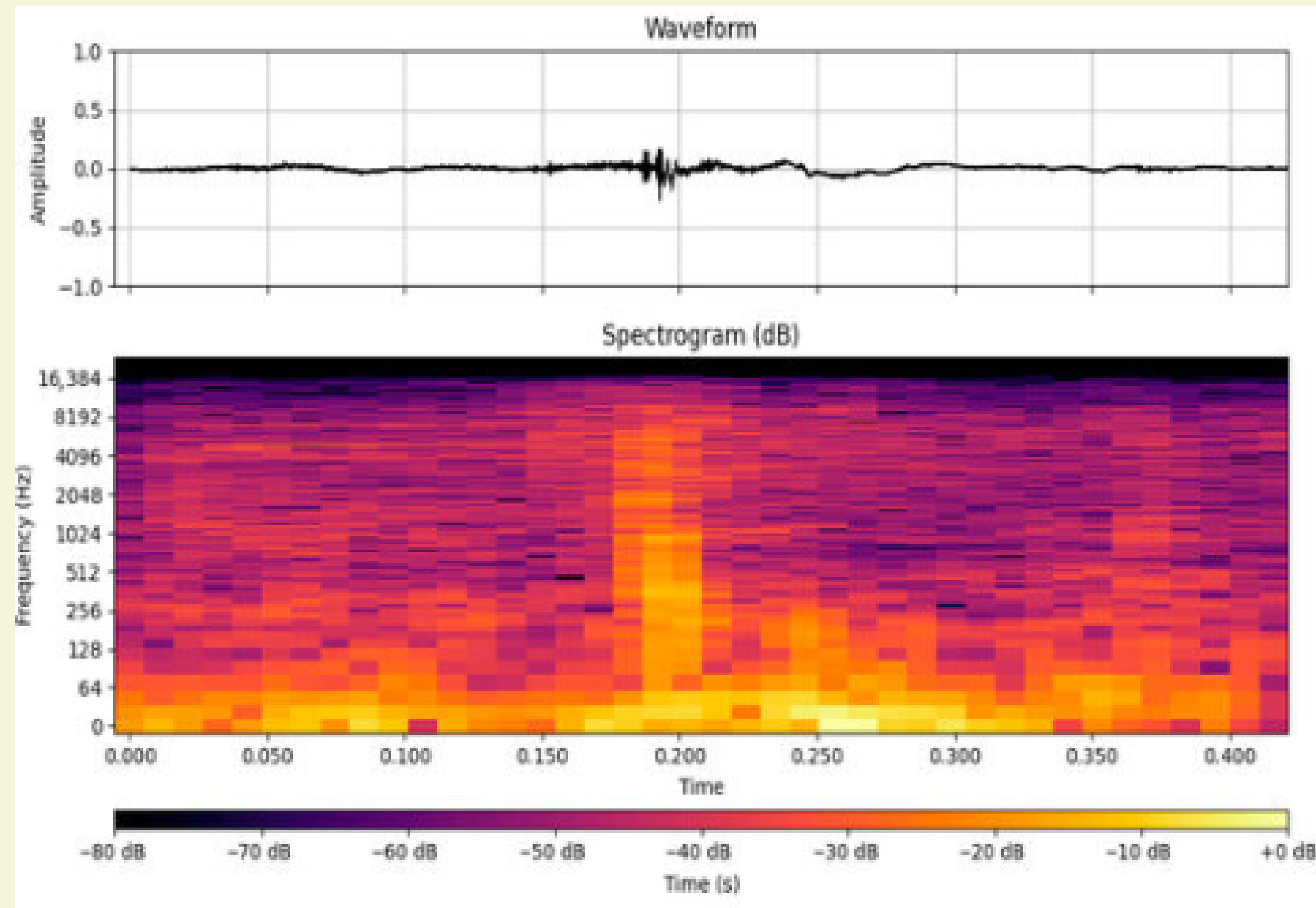
File upload

Deep learning classification

Prehension events output

Spectrogram generation

YOLOv11



Acoustcc data

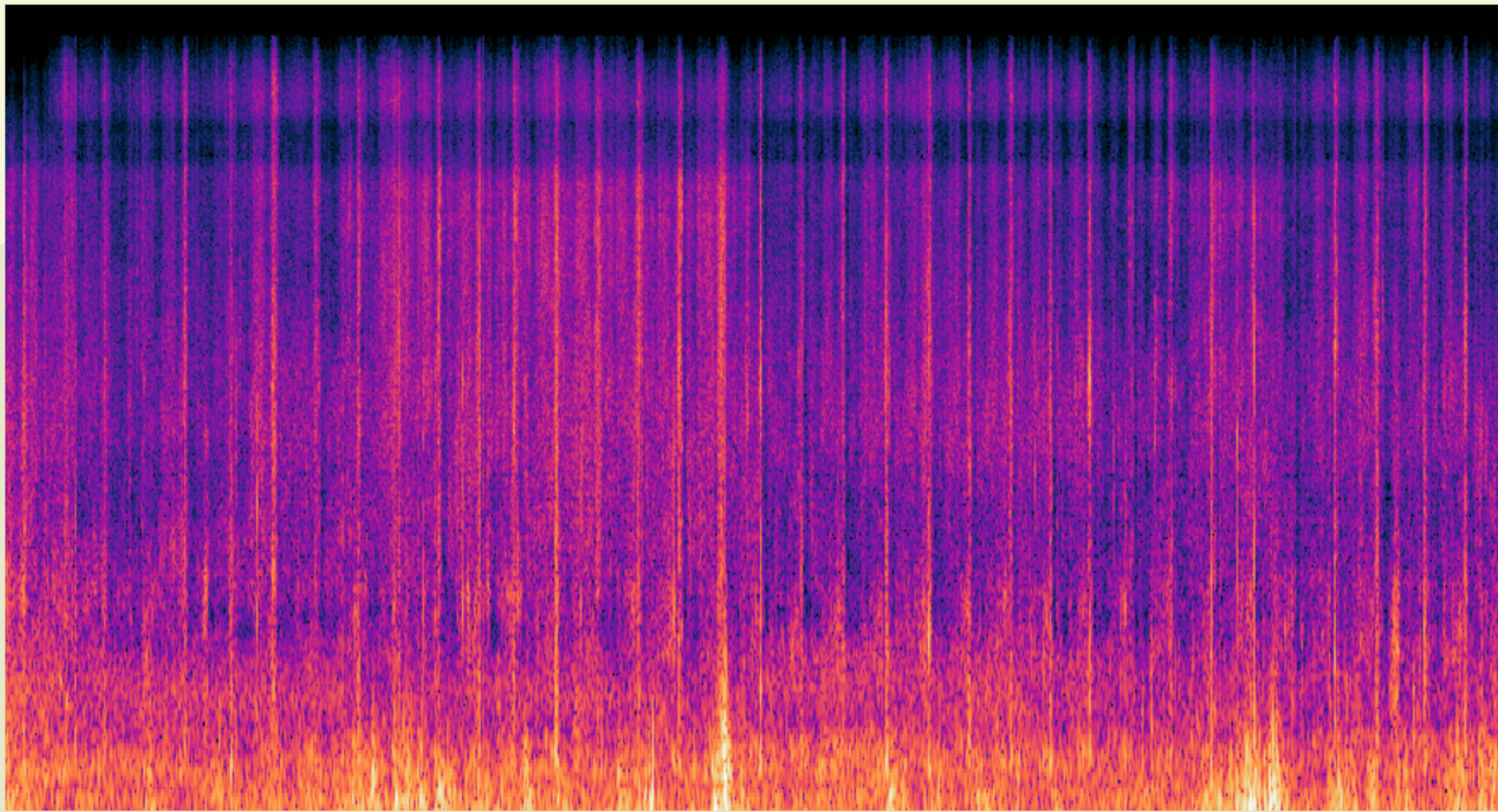
File upload

Deep learning classification

Prehension events output

Spectrogram generation

SPECTROGRAM GENERATION





CLASSES	TRAIN_COUNT	TRAIN_MS	TRAIN_TIME	VAL_COUNT	VAL_MS	VAL_TIME	TEST_COUNT	TEST_MS	TEST_TIME
0 (no prehension)	17172	8586000	02:23:06.000	4294	2147000	00:35:47.000	10549	5274500	1:27:54.500
1 (prehension)	14146	7073000	01:57:53.000	3537	1768500	00:29:28.500	6545	3272500	00:54:32.500





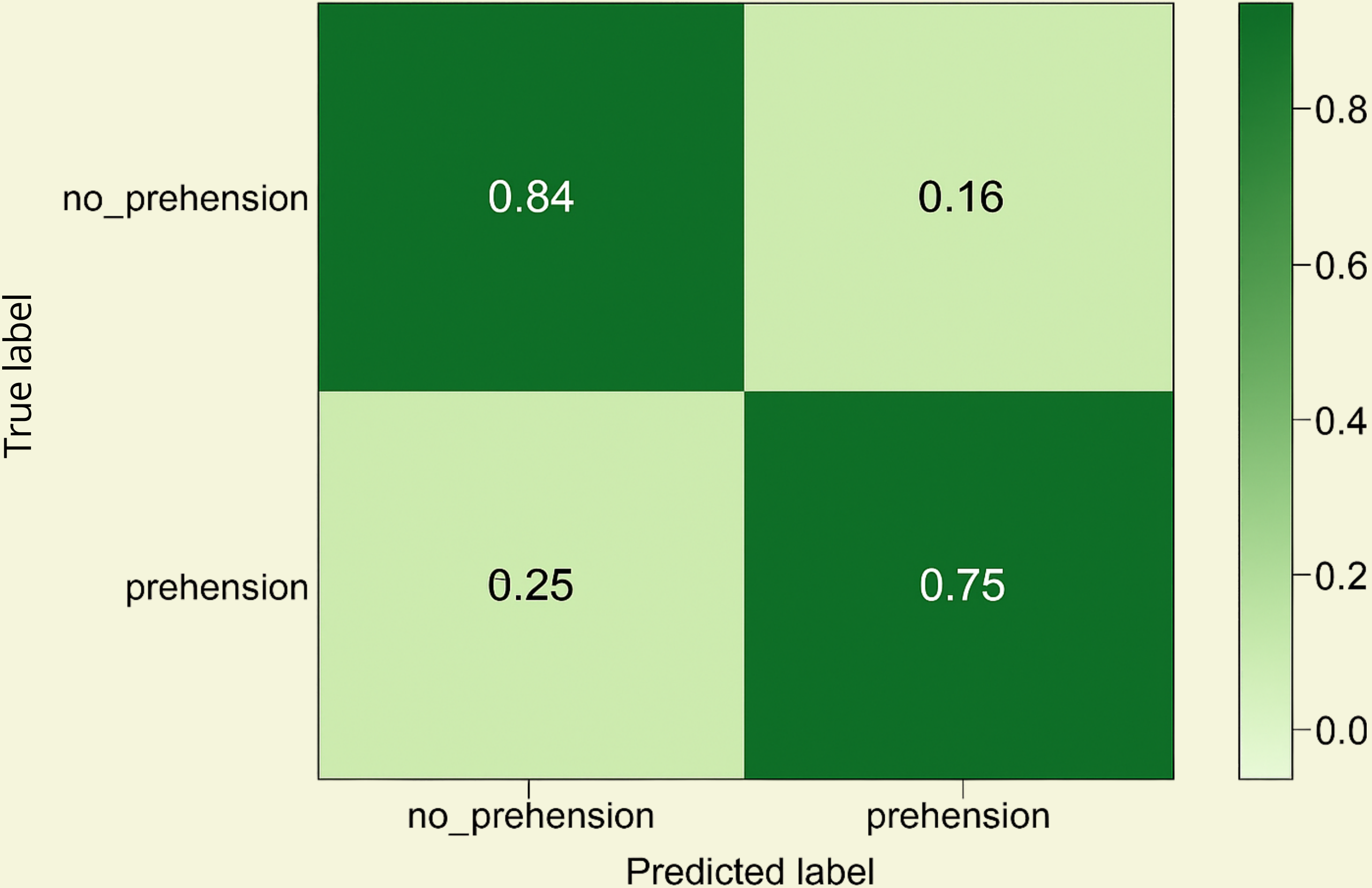
Acoustcc data

File upload

Deep learning classification

Prehension events output

Spectrogram generation



CONCLUSIONS

The platform allows, in a non-invasive way, to estimate the number of prehensions.

$$I_e = T_i \times N_i \times P_i$$

With positive impacts in terms of:

- animal welfare;
- production efficiency;
- environmental impact.